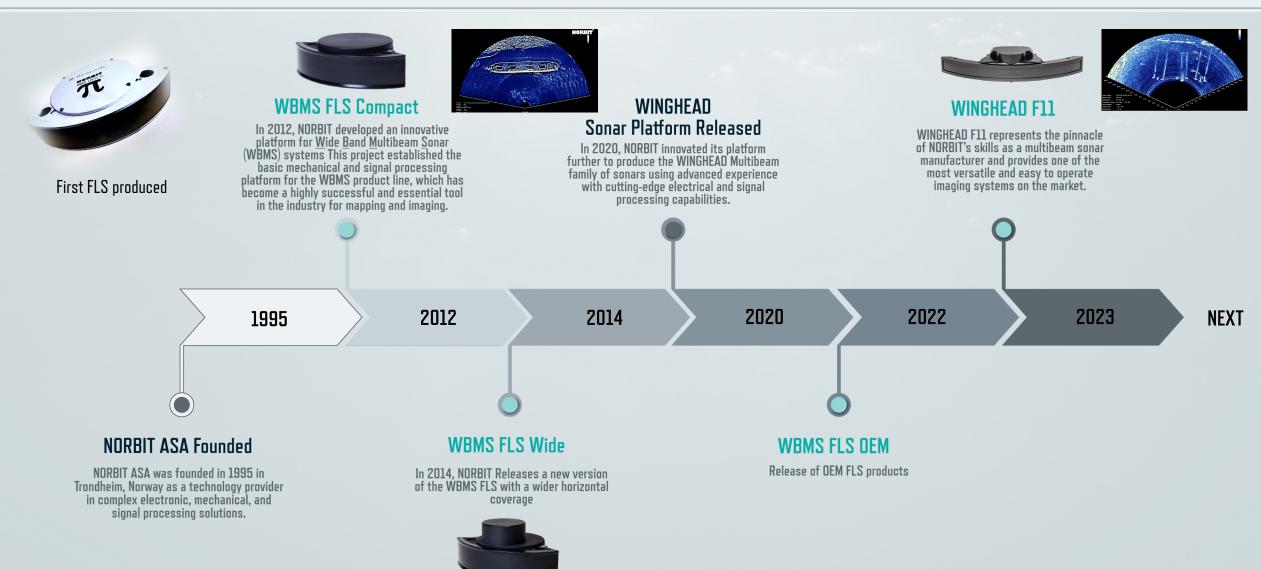


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NORBIT next-generation high-resolution, long-range, forward-looking imaging sonars for multiple deployment operations. WINGHEAD F11



History of NORBIT Imaging Sonars





WINGHEAD F11 Integration All platforms supported









Performance In A Small Form Factor



NORBIT's Carbon Fiber PORTUS Pole for surface vessel work.

Summary of Benefits

- Highest bandwidth processing available in the industry
- Superior range resolution, curved array and signal processing equals unmatched data quality in a compact system.
- NORBIT provides integration support for turnkey solutions requiring custom cables/adaptation to 3rd party connectors.
- Adding additional software processing chains is possible by an agile public interface for real-time or after-action processing.

Technical Highlights

- > Compact system with processing inside the sonar and one interface cable.
- The curved array technology provides 180-degree horizontal coverage and >25-degree vertical coverage for comprehensive area imaging.
- > The 80kHz bandwidth yields <10mm Range Resolution
- > 0.5 deg beams with up to 1024 beams.
- Ultra-compact design for easy installation on most UUV, ASV, ROV, and Surface Vessels.
- Can be combined with NORBIT's GuardPoint Software for intruder detection.
- Standard depth rating 900m or 4500m
- Outputs standard S7K Imagery Format





Real Operational Data Examples

To present results in a meaningful way, the outputs of the WINGHEAD F11 are displayed based on range performance using the following range scales:



Short Range Inspections: Range 1-50m

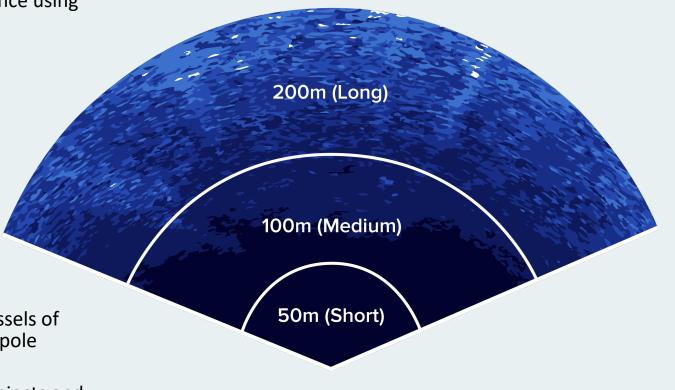
Mid-Range Navigation And Wide Area Search: Range 50-100m



Long Range Detection/Search/Navigation: Range 100-200m

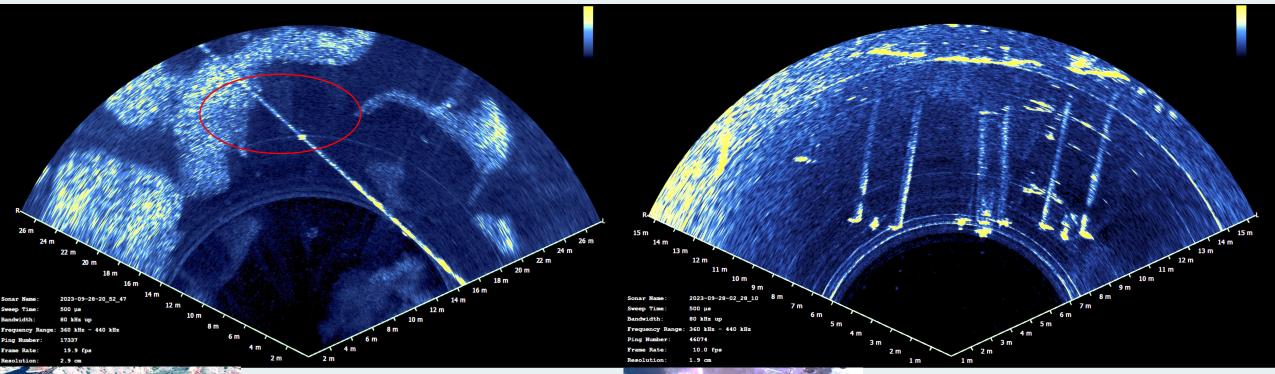
Data was collected using NORBIT's surface vessels or vessels of opportunity equipped with a standard NORBIT PORTUS pole mount and custom angle adjustable brackets.

Various targets were chosen to highlight recognizable objects and features at different ranges.





Results – Short Range Complex Objects and Navigation





Objective: Imaging surface & subsurface structures: surface buoys, line, and fish schools

Range: **35m** Water Depth: **20-40m**



Objective: Imaging approach to floating docks.

Range: 20m

Water Depth: 3-5m



History:

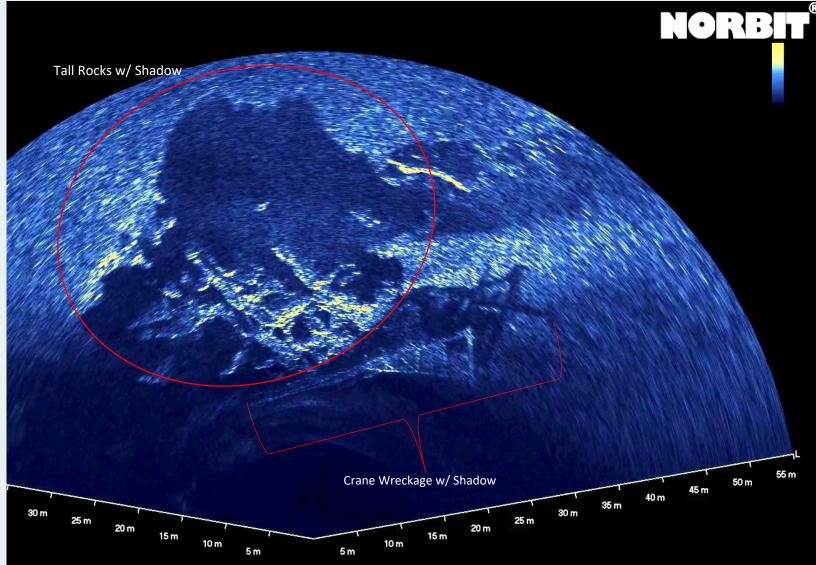
In this image, the superior performance of the WINGHEAD F11 can be seen when imaging details of complex structures ahead of a vehicle. The structure of tall rocks and man-made objects is easily identified in the middle of the river, a high-traffic shipping and recreational waterway that requires constant management as the depth varies widely from 2-5m+ through the year.

Using historical images allows for confirmation of what the sonar detects. In this case, the sonar image shows the wreckage of a crane that was lost during the reconstruction of the Liberty Bridge in Budapest after WWII.



Construction of the central part of the bridge on 12 July 1946 (Source: Fortepan / Hungarian Museum of Technology and Transport / Collection of Historical Photographs / Ganz Collection / TFGY 2017.1.1105)

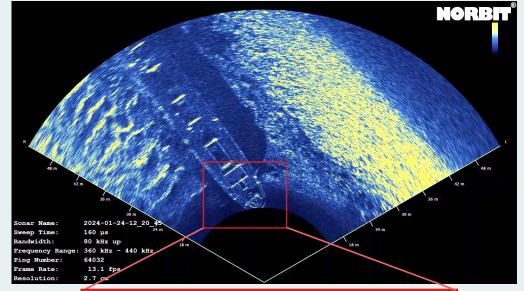
Results – Short Range Search and Recovery, Navigation





Results Mid-Range

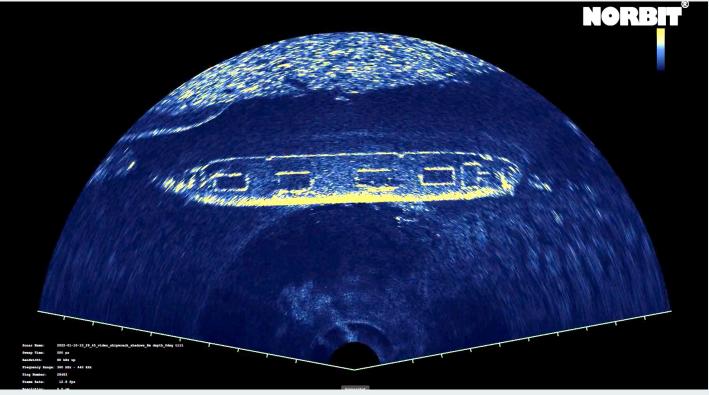
Detailed Inspection Using Acoustic Zoom





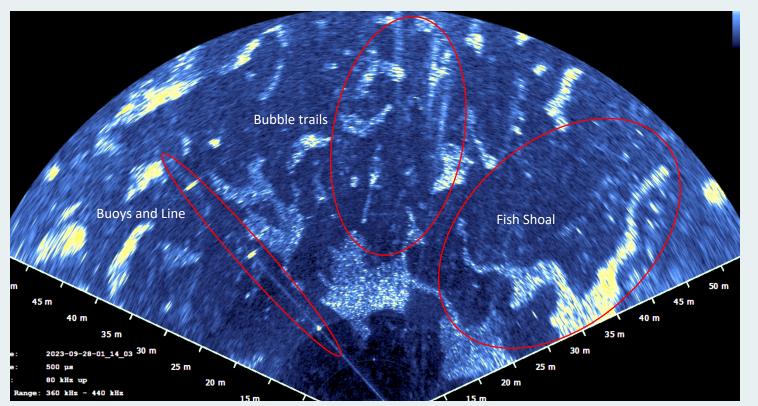
The Acoustic Zoom feature in NORBIT GUI allows for detailed inspection/analysis by an operator.

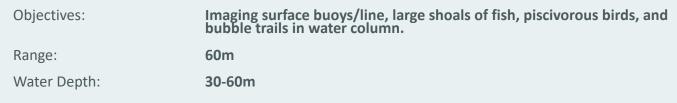
Objective:Investigate a Sunken barge next to the shoreline in high
traffic areaRange:50-60mWater Depth:5-8m

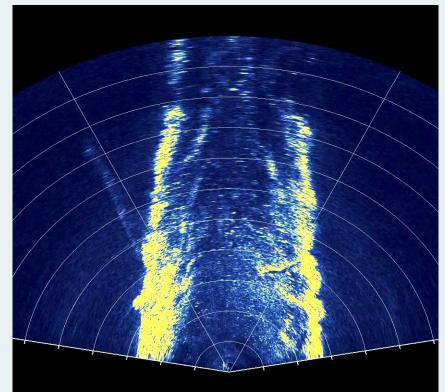




Results Mid-Range Environmental & Navigation Imaging



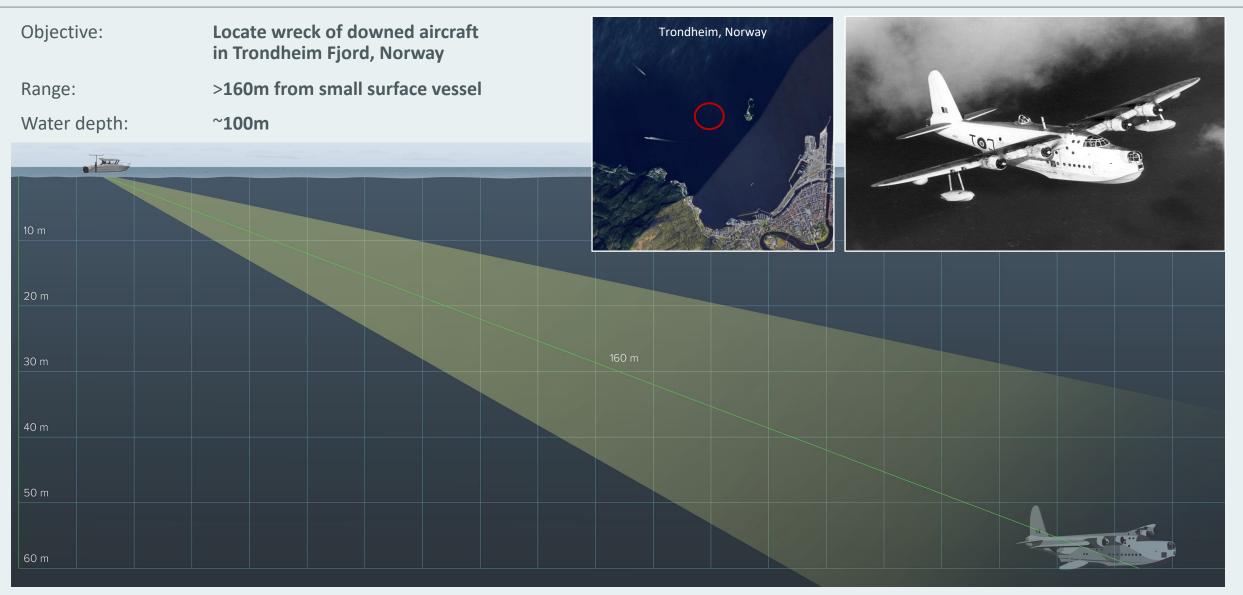




Objective:	Narrow channel navigation in shallow water
Range:	50m+
Water Depth:	5m

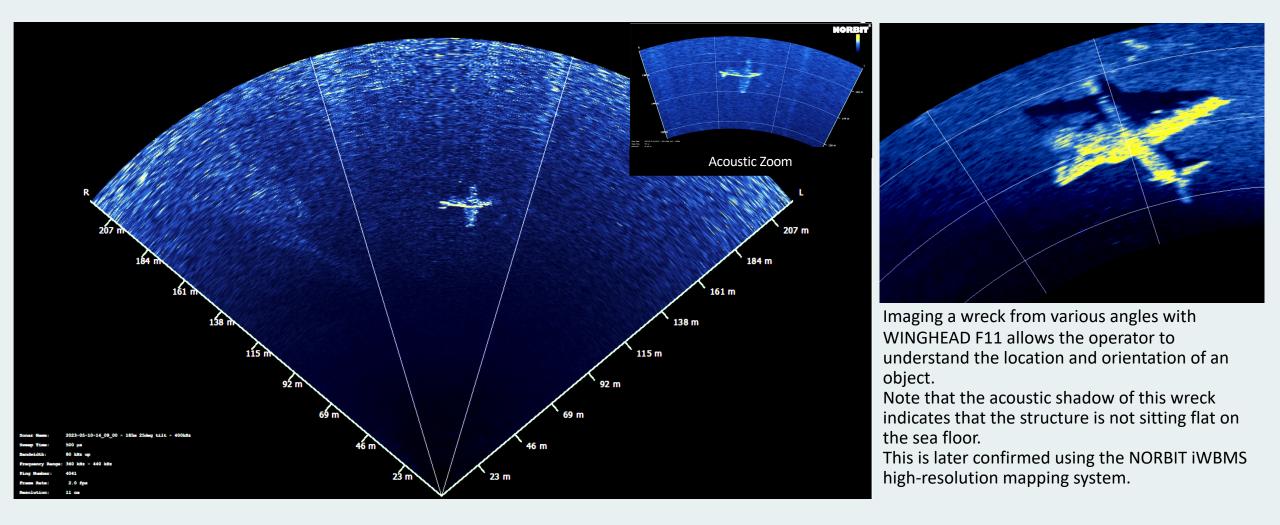


Introduction to Long Range Imaging Airplane Wreck





Results - Long Range Imaging Airplane Wreck



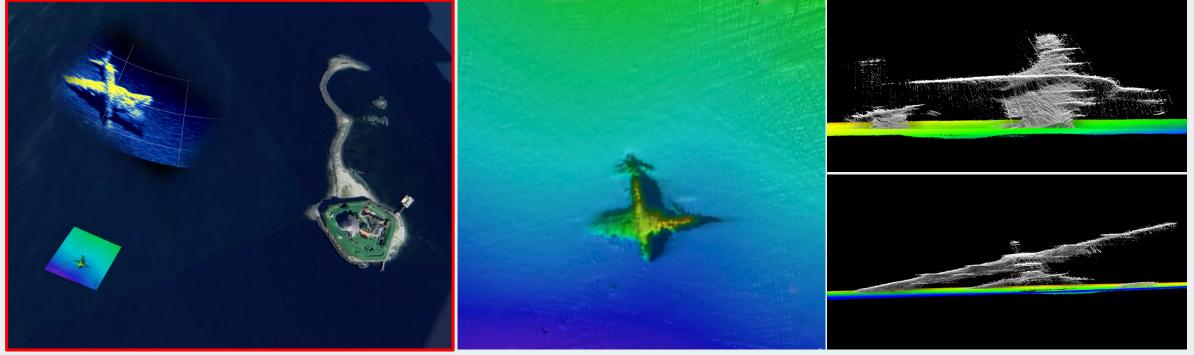


Results - Long Range Imaging Optimising mapping activity



Once an object of interest is located using the imaging sonar, a detailed bathymetry map can be quickly made using a mapping sonar, such as the NORBIT iWBMS. Combining imaging from WINGHEAD F11 for long range localization enables a more efficient definition of a specific survey area, thus saving time.

In this example we show the outputs of the mapping survey that confirms the location and orientation of the wreck on the seabed.



Mapped Wreckage DTM + WINGHEAD F11 Image

Detailed Point Cloud from NORBIT iWBMS



WINGHEAD F11 One Sonar, Many Applications



Applications:

- Navigational Aid, Obstacle Avoidance
- MCM, Intruder Detection
- Offshore Energy Exploration
- Dive Team Support, EOD, S&R
- Underwater Infrastructure Inspection
- Marine Research and Exploration
- Fisheries and Aquaculture

Explore More:

FLS Sonar Family



WINGHEAD Sonar Family



Product Accessories and Software



Case Study: Rapid Environmental Assessment



- explore more -



For more information contact:

subsea@norbit.com