# Memorial University – Marine Institute & Public Works, Government Services Canada

Trial of NORBIT iWBMSh-STX Holyrood, NL 5 October, 2018



## Overview

09:56	09:55	Depart Delta Hotel in St. John's
10:23 =		
10:51	10:55	Commence setting up Portus Pole in Holyrood
11:18 _	11:20	Portus Pole build complete
11:45 -		
12:13	12:00	Drill holes for mounting plate complete
12.13	12:29	Depart dock for survey area
12:40		
13:07 -	13:15	Complete setting up Hypack, INS offsets, heading alignment calibration
13:35 =		(GAMS)
14:02 =		
	14:25	Complete patch test, sound speed profiles
14:30	14:34	and shoreline survey area of 1km x 330m Return to dock
14:57 =		
15:24	15:20	Depart Holyrood
15:52 -	15:50	Ship equipment out at FedEx in St. John's



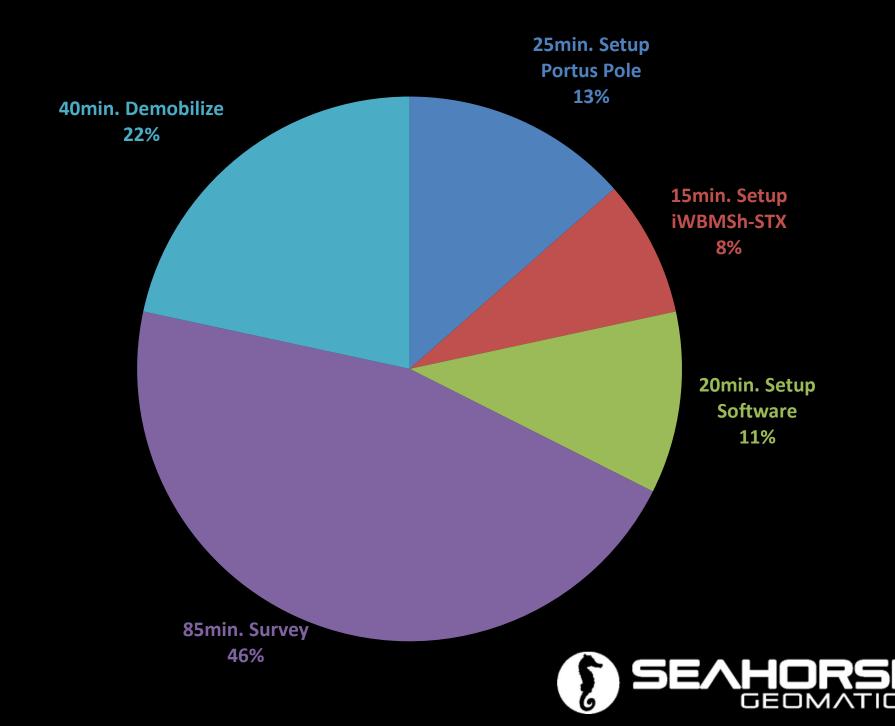
Complete Survey Kit:

 Case 1: Norbit iWBMSh-STX Sonar Rx, Tx, Probe IMU Mounting Bracket/Fairing Sound Profiler (optional) LiDAR (optional)
 Case 2: Portus Pole
 Backpack: Laptop & lunch

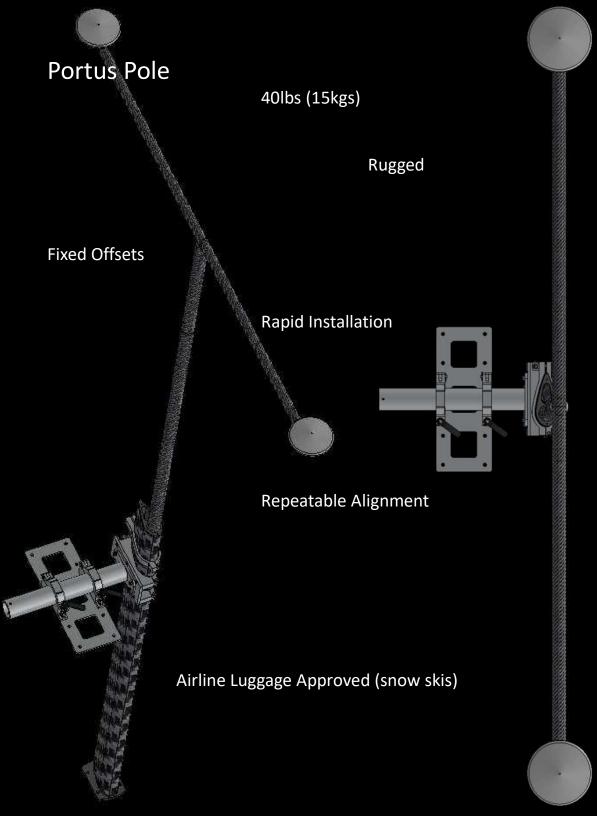




## **185 MINUTE SURVEY: VESSEL OF OPPORTUNITY**



S



Single Portus Case (20lbs  $\rightarrow$  7.5kgs)



Norbit iWBMSh-STX

**SEAHOR** 

GEOM/

5

## NORBIT iWBMSh-STX

1.8° x 1.9° @200kHz 0.9° x 0.9° @400kHz 0.65° x 0.65° @550kHz 0.51° x 0.51° @700kHz

**Curved Array** 

- Minimal beam spreading
- Low impact due to incorrect sound speed
- Compact size
- Allows FM for highest resolution

#### 80kHz FM Signal

- Highest SNR for all beams
  - For best data quality
  - For widest possible swath
- No compromising range for resolution
- Noise resistant (other acoustics)

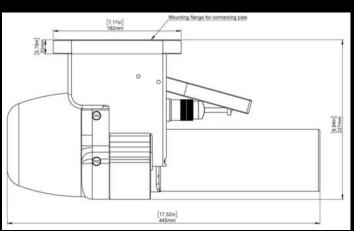
#### STX – Steerable Transmitter

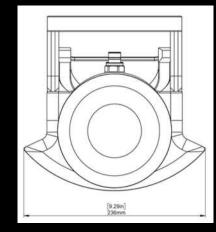
- Pitch stabilization
- 3D scanning for best incidence angle
- Forward looking route clearance
- Water column inspection at discrete angles

#### Integrated GNSS/INS

- Applanix OceanMaster (AP30)
- No cabling / integration
- Integrated GUI with setup wizard & monitor
- May be decoupled for discrete operation

#### Weight: 30lbs $\rightarrow$ 11kgs (complete wet end incl. bracket)









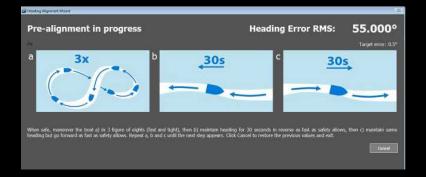


## Straightforward Setup

#### Offsets from Portus Pole Manual (save to reloadable config file)

Lever Arms Using Standard 1.881m Sonar Pole	+Fwd	+Stbd	+Dwn	+Dwn
			1.5m Ant. Mast	0.5m Ant. Mast
Bttm Center Sonar Flange to Bttm Aft Ant.	-0.955	0.000	-3.336	-2.334
Bttm Center Sonar Flange to Bttm Fwd Ant.	1.043	0.000	-3.336	-2.334
For Applanix integrated NORBIT Systems: Above Mount. WBNMS GUI (10.3 +) will add rema		•		

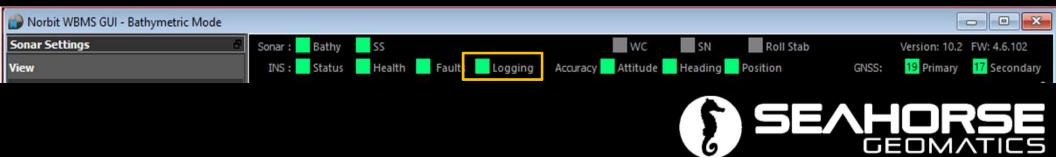
#### Complete Heading Alignment (GAMS) calibration by following on-screen directions

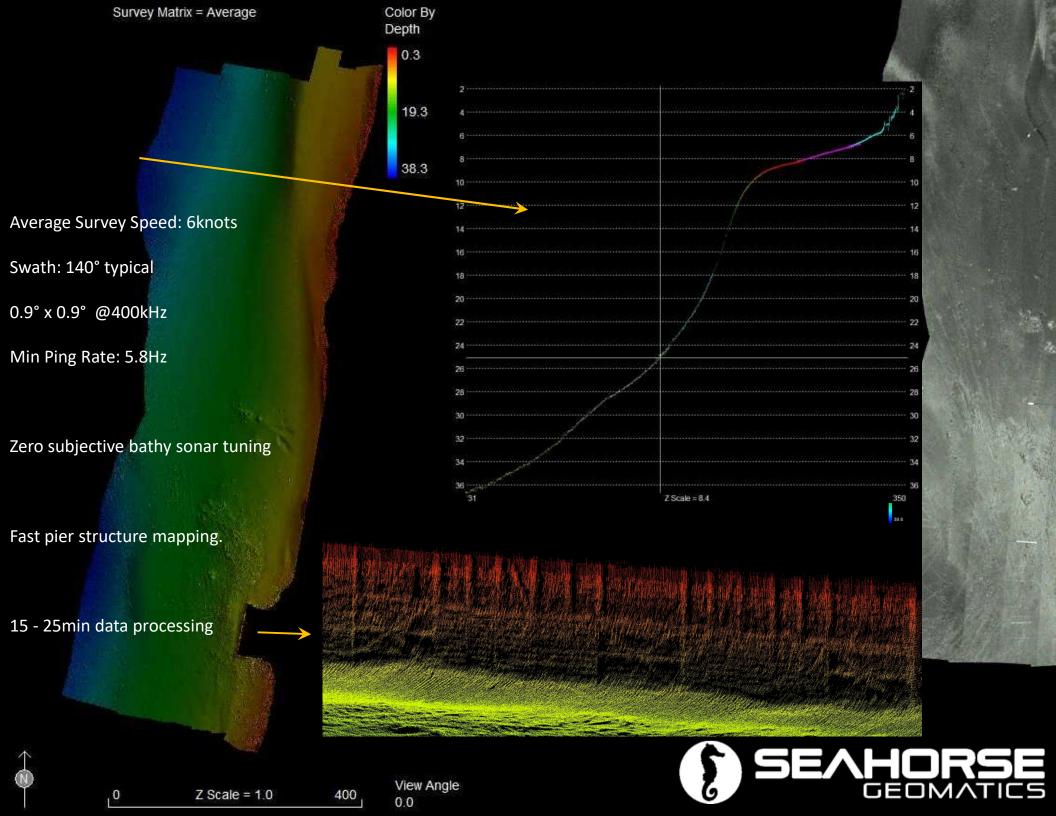


INS Setup Wizard		
Primary Antenna 📃 Tri	mble 540AP (58mm, Standard)	
Measure Point. Top Ce	inter of Bracket	
· WBHS Ref. Point to Mea	num Pont	
	10.000	
Measure Point to Antere		
+Fwd	-0.955 m	
+Stbd	0.000 m	-
+Down	-3.336 m	
Heading Threshold	Default Value	
researing intranional	Detaut value:	
Heading Alignment Headin Primary to Secondary Ar		
<ul> <li>Primary to Secondary Ar</li> </ul>	nterma Baseline Vector	
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Enter offsets into Hypack/Hysweep (from COR at Waterlevel at ~zero roll) to sonar reference for Norbit and Applanix device.

## Survey! Monitor quality from a single interface. All GNSS/INS data quality and solution/sensor status is shown. Rest assured, Applanix POS Pac data is logged automatically for Heave/PPP/PPK

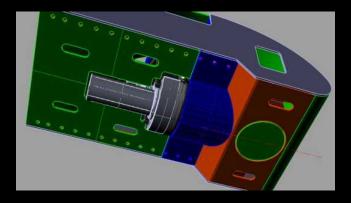




## Hull Mounting Examples

US Corps of Engineers (4 vessels with permanent hull mounts)











### **Recommended NORBIT Options**

For 0.3m to 175m (max 330m) or indicate Long Range for 0.3m to 600m

iWBMS-Narrow iWBMSh-Narrow iWBMS-STX iWBMSh-STX

Portus Pole Kit Dual head bracket <u>Hull mount /tailored mount design</u>

NORBIT Profiler 100m or 500m (by AML)

Lidar

Include WBMS 200-700kHz, Snippets, Watercolumn, Sidescan, Applanix, Sound Probe, Bracket and Fairing





On-site basic/advanced training (utilizing Hypack/Hysweep and/or QINSy/Qimera